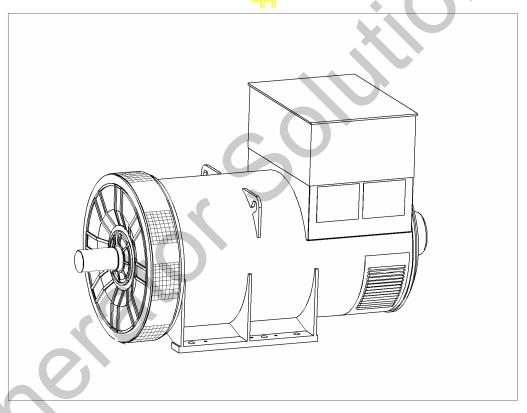
# STAMFORD

**PI734E** - Winding 312

Technica Data Sheet



#### **PI734E**



#### **SPECIFICATIONS & OPTIONS**

#### **STANDARDS**

Stamford industrial generators meet the requirements of BS EN 60034 and the relevant sections of other national and international standards such as BS5000, VDE 0530, NEMA MG1-32, IEC60034, CSA C22.2-100, AS1359. Other standards and certifications can be considered on request.

#### DESCRIPTION

The STAMFORD PI range of synchronous ac generators are brushless with a rotating field. They are separately excited by the STAMFORD Permanent Magnet Generator (PMG). This is a shaft mounted, high frequency, pilot exciter which provides a constant supply of clean power via the Automatic Voltage Regulator (AVR) to the main exciter. The main exciter output is fed to the main rotor, through a full wave bridge rectifier, protected by surge suppression.

#### **VOLTAGE REGULATORS**

The PI range generators, complete with a PMG, are available with one of two AVRs. Each AVR has soft start voltage build up and built in protection against sustained over-excitation, which will de-excite the generator after a minimum of 8 seconds.

Underspeed protection (UFRO) is also provided on both AVRs. The UFRO will reduce the generator output voltage proportional to the speed of the generator below a presettable level.

The **MX341 AVR** is two phase sensed with a voltage regulation of  $\pm 1$  %. (see the note on regulation).

The MX321 AVR is 3 phase rms sensed with a voltage regulation of 0.5% rms (see the note on regulation). The UFRO circuit has adjustable slope and dwell for controlled recovery from step loads. An over voltage protection circuit will shutdown the output device of the AVR, it can also trip an optional excitation circuit breaker if required. As an option, short circuit current limiting is available with the addition of current transformers.

Both the MX341 and the MX321 need a generator mounted current transformer to provide quadrature droop characteristics for load sharing during parallel operation. Provision is also made for the connection of the STAMFORD power factor controller, for embedded applications, and a remote voltage trimmer.

#### WINDINGS & ELECTRICAL PERFORMANCE

All generator stators are wound to 2/3 pitch. This eliminates triplen (3rd, 9th, 15th ...) harmonics on the voltage waveform and is found to be the optimum design for trouble-free supply of non-linear loads. The 2/3 pitch design avoids excessive neutral currents sometimes seen with higher winding pitches. A fully connected damper winding reduces oscillations during paralleling. This winding, with the 2/3 pitch and carefully selected pole and tooth designs, ensures very low levels of voltage waveform distortion.

#### **TERMINALS & TERMINAL BOX**

Standard generators feature a main stator with 6 ends brought out to the terminals, which are mounted on the frame at the non-drive end of the generator. A sheet steel terminal box contains the AVR and provides ample space for the customers' wiring and gland arrangements. It has removable panels for easy access.

#### **SHAFT & KEYS**

All generator rotors are dynamically balanced to better than BS6861:Part 1 Grade 2.5 for minimum vibration in operation. Two bearing generators are balanced with a half key.

#### INSULATION/IMPREGNATION

The insulation system is class 'H', and meets the requirements of UL1446.

All wound components are impregnated with materials and processes designed specifically to provide the high build required for static windings and the high mechanical strength required for rotating components.

#### **QUALITY ASSURANCE**

Generators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.

#### **NOTE ON REGULATION**

The stated voltage regulation may not be maintained in the presence of certain radio transmitted signals. Any change in performance will fall within the limits of Criteria 'B' of EN 61000-6-2:2001. At no time will the steady-state voltage regulation exceed 2%.

#### **DE RATES**

All values tabulated on page 8 are subject to the following reductions

5% when air inlet filters are fitted.

10% when IP44 Filters are fitted.

3% for every 500 metres by which the operating altitude exceeds 1000 metres above mean sea level. 3% for every 5°C by which the operational ambient temperature exceeds 40°C.

Note: Requirement for operating in an ambient temperature exceeding 60°C must be referred to the factory.

Note: Continuous development of our products entitles us to change specification details without notice, therefore they must not be regarded as binding.

Front cover drawing is typical of the product range.

# **STAMFORD**

#### **PI734E**

#### **WINDING 312**

CONTROL SYSTEM	SEPARATEL	PARATELY EXCITED BY P.M.G.								
A.V.R.	MX341	MX321								
VOLTAGE REGULATION	±1%	± 0.5 %	With 4% ENGINE GOVERNING							
SUSTAINED SHORT CIRCUIT	REFER TO S	EFER TO SHORT CIRCUIT DECREMENT CURVES (page 7)								

SUSTAINED SHORT CIRCUIT	REFER TO	SHURT CIRC	UII DECKE	IENI CURVI	=5 (page 7)									
INSULATION SYSTEM				CLAS	SS H									
PROTECTION	IP23													
RATED POWER FACTOR	0.8													
STATOR WINDING	DOUBLE LAYER LAP													
WINDING PITCH	TWO THIRDS													
WINDING LEADS	6													
MAIN STATOR RESISTANCE		0.00	0093 Ohms P	ER PHASE A	T 22°C STA	R CONNECT	ED							
MAIN ROTOR RESISTANCE				2.17 Ohm:	s at 22°C									
EXCITER STATOR RESISTANCE				17.5 Ohm:	s at 22°C									
EXCITER ROTOR RESISTANCE			0.06	3 Ohms PER	PHASE AT 2	22°C								
R.F.I. SUPPRESSION	BS EI	N 61000-6-2 8	& BS EN 610	00-6-4,VDE 0	875G, VDE 0	0875N. refer to	o factory for o	thers						
WAVEFORM DISTORTION			< 1.5% NON-											
MAXIMUM OVERSPEED				2250 R	ev/Min									
BEARING DRIVE END				BALL. 6	228 C3									
BEARING NON-DRIVE END		BALL. 6319 C3												
		1 BE/	ARING			2 BEA	RING							
WEIGHT COMP. GENERATOR			6 kg		3506 kg									
WEIGHT WOUND STATOR			7 kg		1747 kg									
WEIGHT WOUND ROTOR		_	4 kg		1432 kg									
WR2 INERTIA			kgm <sup>2</sup>		44.4891 kgm <sup>2</sup>									
SHIPPING WEIGHTS in a crate		<del></del>	29kg		3575kg									
PACKING CRATE SIZE	X	216 x 105	_		216 x 105 x 154(cm)									
		50	Hz		60 Hz									
TELEPHONE INTERFERENCE		THF	<2%		TIF<50									
COOLING AIR		2.69 m³/se	c 5700 cfm		3.45 m³/sec 7300 cfm									
VOLTAGE STAR	380/220	400/231	415/240	440/254	416/240	440/254	460/266	480/277						
kVA BASE RATING FOR REACTANCE VALUES	1845	1900	1900	1865	2070	2210	2255	2300						
Xd DIR. AXIS SYNCHRONOUS	3.18	2.96	2.75	2.40	3.84	3.67	3.42	3.21						
X'd DIR. AXIS TRANSIENT	0.19	0.18	0.17	0.15	0.23	0.22	0.21	0.19						
X"d DIR. AXIS SUBTRANSIENT	0.14	0.13	0.12	0.11	0.17	0.16	0.15	0.14						
Xq QUAD. AXIS REACTANCE	2.04	1.90	1.76	1.54	2.47	2.36	2.20	2.06						
X"q QUAD. AXIS SUBTRANSIENT	0.29	0.27	0.25	0.22	0.35	0.33	0.31	0.29						
XL LEAKAGE REACTANCE	0.04	0.03	0.03	0.03	0.04	0.04	0.04	0.04						
X2 NEGATIVE SEQUENCE	0.20	0.19	0.17	0.15	0.24	0.23	0.22	0.20						
X <sub>0</sub> ZERO SEQUENCE	0.02	0.02	0.02	0.02	0.03	0.03	0.03	0.03						
REACTANCES ARE SATURA	TED	V	/ALUES ARE			ND VOLTAGI	E INDICATED	)						
T'd TRANSIENT TIME CONST.				0.14										
T''d SUB-TRANSTIME CONST.				0.0										
T'do O.C. FIELD TIME CONST.  Ta ARMATURE TIME CONST.				0.0										
SHORT CIRCUIT RATIO	+			1/2										
				.,,										

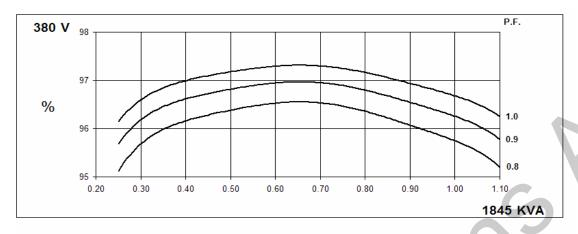
50 Hz

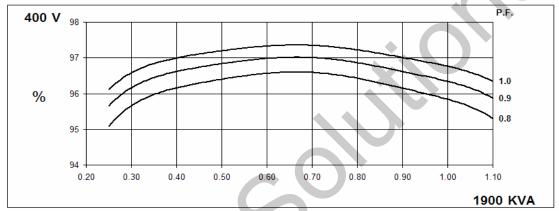
## PI734E

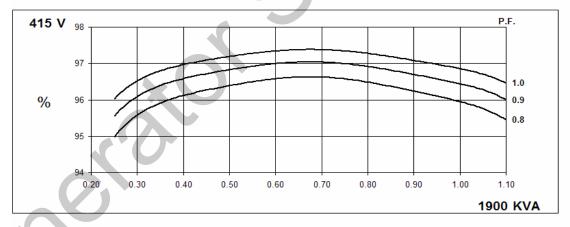
#### **STAMFORD**

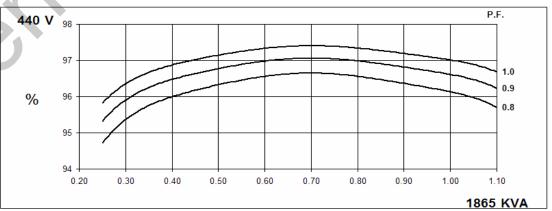
#### Winding 312

#### THREE PHASE EFFICIENCY CURVES









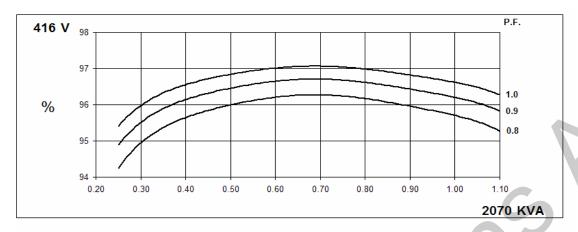
60 Hz

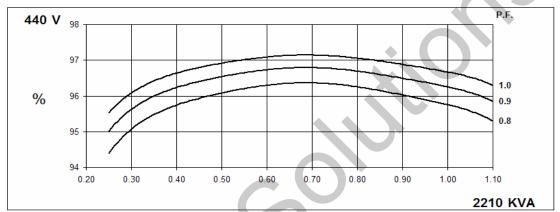
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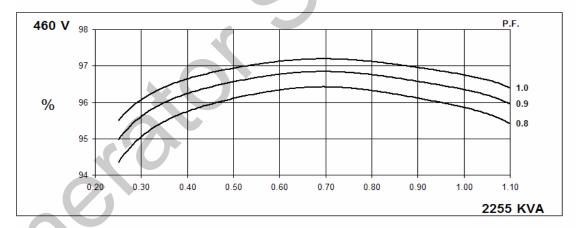
#### **STAMFORD**

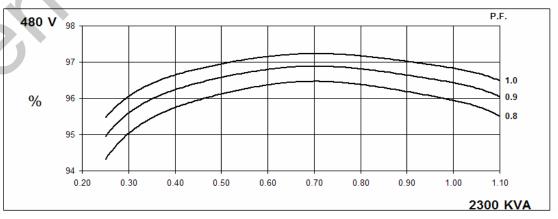
#### Winding 312

#### THREE PHASE EFFICIENCY CURVES





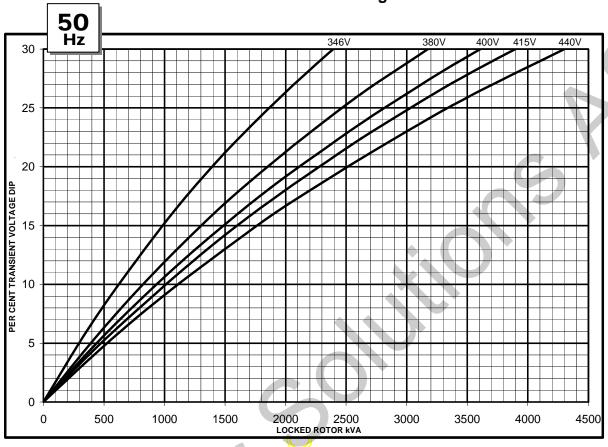


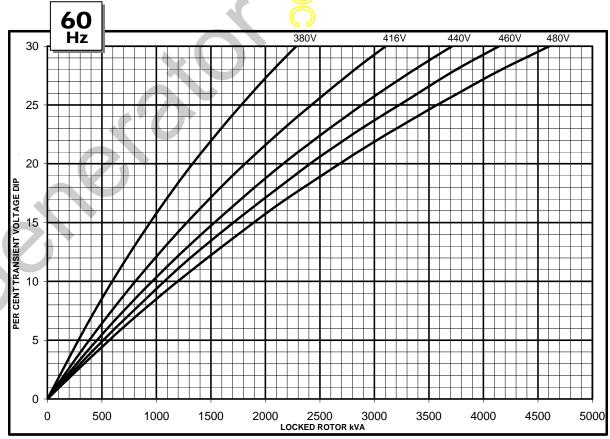




**PI734E** Winding 312

# **Locked Rotor Motor Starting Curve**

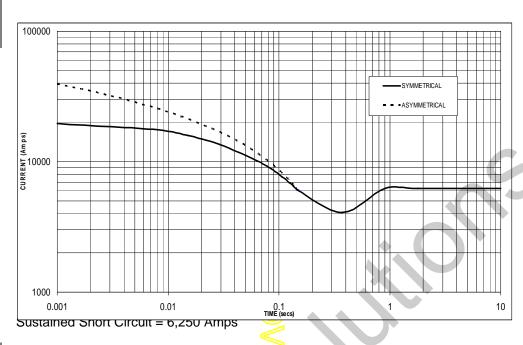




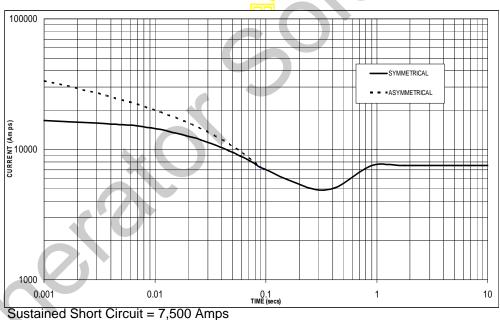


# Three-phase Short Circuit Decrement Curve. No-load Excitation at Rated Speed Based on star (wye) connection.





60 Hz



#### Note 1

The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage:

50	Hz	60	Hz
Voltage	Factor	Voltage	Factor
380v	x 1.00	416v	x 1.00
400v	x 1.05	440v	x 1.06
415v	x 1.09	460v	x 1.10
440v	x 1.16	480v	x 1.15

The sustained current value is constant irrespective of voltage level

#### Note 2

The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit:

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

All other times are unchanged

#### Note 3

Curves are drawn for Star (Wye) connected machines.



#### **PI734E**

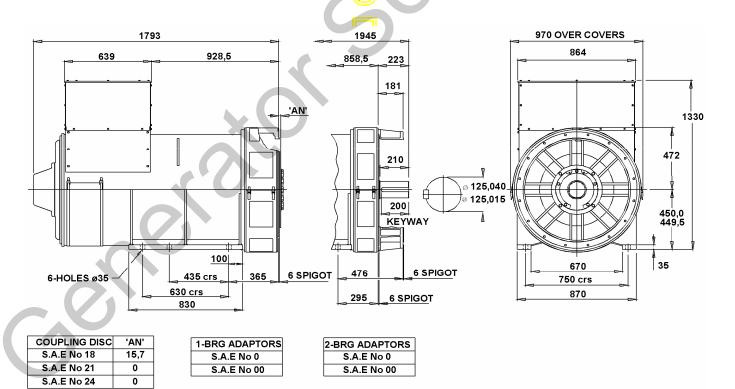
#### Winding 312 / 0.8 Power Factor

#### **RATINGS**

Cla	ass - Temp Rise	Co	ont. F -	105/40°	.C	Cont. H - 125/40°C				Sta	andby -	150/40	°C	Standby - 163/27°C			
<b>50</b> Hz	_		400	415	440	380	400	415	440	380	400	415	440	380	400	415	440
	kVA	1715	1770	1770	1735	1845	1900	1900	1865	1920	1980	1980	1940	1975	2035	2035	1995
	kW	1372	1416	1416	1388	1476	1520	1520	1492	1536	1584	1584	1552	1580	1628	1628	1596
	Efficiency (%)	95.9	96.0	96.1	96.3	95.7	95.8	96.0	96.1	95.6	95.7	95.8	96.1	95.5	95.6	95.8	96.0
	kW Input	1431	1475	1473	1441	1542	1587	1583	1553	1607	1655	1653	1615	1654	1703	1699	1663

•	0Hz Star (V)		440	460	480	416	440 460	480	416	440	460	480	416	440	460	480
		1935			2140		2210 2255		2155		2345	2395	2215	2365		2465
	kW	1548	1644	1680	1712	1656	1768 804	1840	1724	1840	1876	1916	1772	1892	1932	1972
	Efficiency (%)	95.8	95.9	96.0	96.1	95.7	95.8 95.9	95.9	95.6	95.7	95.8	95.9	95.5	95.6	95.7	95.8
	kW Input	1616	1714	1750	1781	1730	1846 1881	1919	1803	1923	1958	1998	1855	1979	2019	2058

### DIMENSIONS



# APPROVED DOCUMENT

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